

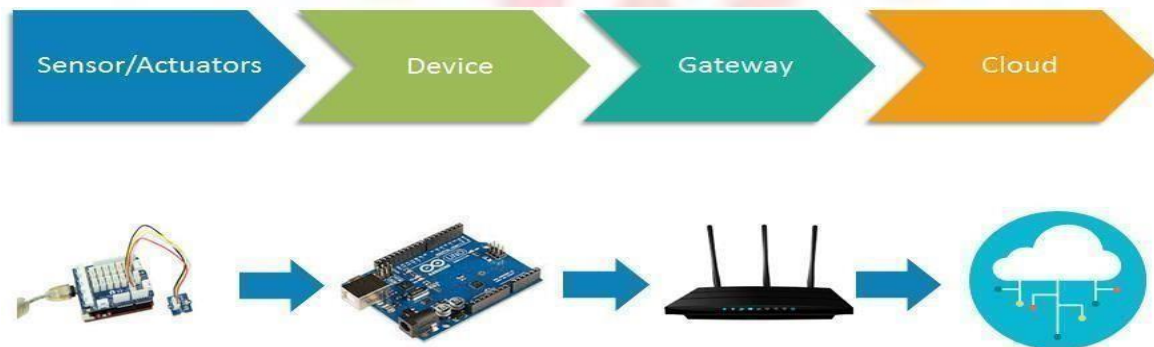
UNIT- 3

1. IOT architecture

State of the art

IoT architecture varies from solution to solution, based on the type of solution which we intend to build. IoT as a technology majorly consists of four main components, over which an architecture is framed.

- 1) Sensors
- 2) Devices
- 3) Gateway
- 4) Cloud



Stages of IoT Architecture

Stage 1: Sensors/actuators

Sensors collect data from the environment or object under measurement and turn it into useful data. Think of the specialized structures in your cellphone that detect the directional pull of gravity and the phone's relative position to the “thing” we call the earth and convert it into data that your phone can use to orient the device.

Actuators can also intervene to change the physical conditions that generate the data. An actuator might, for example, shut off a power supply, adjust an air flow valve, or move a robotic gripper in an assembly process.

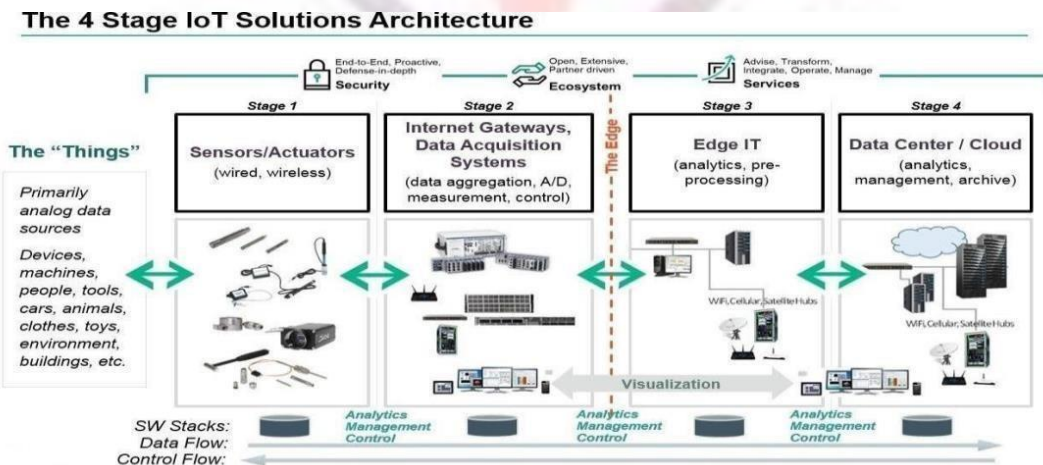
The sensing/actuating stage covers everything from legacy industrial devices to robotic camera systems, water level detectors, air quality sensors, accelerometers, and heart rate monitors. And the scope of the IoT is expanding rapidly, thanks in part to low-power wireless sensor network technologies and Power over Ethernet, which enable devices on a wired LAN to operate without the need for an A/C power source.

Stage2:-

The Internet gateway

The data from the sensors starts in an analog form. That data needs to be aggregated and converted into digital streams for further processing downstream. Data acquisition systems (DAS) perform these data aggregation and conversion functions. The DAS connects to the sensor network, aggregates outputs, and performs the analog-to-digital conversion. The Internet gateway receives the aggregated and digitized data and routes it over Wi-Fi, wired LANs, or the Internet, to Stage 3 systems for further processing. Stage 2 systems often sit in close proximity to the sensors and actuators.

For example, a pump might contain a half-dozen sensors and actuators that feed data into a data aggregation device that also digitizes the data. This device might be physically attached to the pump. An adjacent gateway device or server would then process the data and forward it to the Stage 3 or Stage 4 systems. Intelligent gateways can build on additional, basic gateway functionality by adding such capabilities as analytics, malware protection, and data management services. These systems enable the analysis of data streams in realtime.



Stage 3:-Edge IT

Once IoT data has been digitized and aggregated, it's ready to cross into the realm of IT. However, the data may require further processing before it enters the data center. This is where edge IT systems, which perform more analysis, come into play. Edge IT processing systems may be located in remote offices or other edge locations, but generally these sit in the facility or location where the sensors reside closer to the sensors, such as in a wiring closet. Because IoT data can easily eat up network bandwidth and swamp your data center resources, it's best to have systems at the edge capable of performing analytics as a way to lessen the burden on core IT infrastructure. You'd also face security concerns, storage issues, and delays processing the data. With a staged approach, you can preprocess the data, generate meaningful results, and pass only those on. For example, rather than passing on raw vibration data for the pumps, you could aggregate and convert the data, analyze it, and send only projections as to when each device will fail or need service.

Stage 4:-

The data center and cloud

Data that needs more in-depth processing, and where feedback doesn't have to be immediate, gets forwarded to physical data center or cloud-based systems, where more powerful IT systems can analyze, manage, and securely store the data. It takes longer to get results when you wait until data reaches Stage 4, but you can execute a more in-depth analysis, as well as combine your sensor data with data from other sources for deeper insights. Stage 4 processing may take place on-premises, in the cloud, or in a hybrid cloud system, but the type of processing executed in this stage remains the same, regardless of the platform.

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Script.py

1. a=5
2. print(a,"isof type",type(a))
3. a=2.0
4. print(a,"isof type",type(a))
5. a=1+2j
6. print(a,"iscomplexnumber?",isinstance(1+2j,complex))

Integers can be of any length, it is only limited by the memory available. A floating point number is accurate up to 15 decimal places. Integer and floating points are separated by decimal points. 1 is integer, 1.0 is floating point number. Complex numbers are written in the form, $x + yj$, where x is the real part and y is the imaginary part. Here are some examples.

```
>>> a = 1234567890123456789
```

```
>>> a
```

```
1234567890
```

```
123456789
```

```
>>> b = 0.1234567890123456789
```

```
>>> b
```

```
0.12345678
```

```
901234568
```

```
>>> c = 1+2j
```

```
>>> c(1+2j)
```

Python List

List is an ordered sequence of items. It is one of the most used data type in Python and is very flexible. All the items in a list do not need to be of the same type. Declaring a list is pretty straight forward. Items separated by commas are enclosed within brackets [].

```
>>>a=[1,2.2,  
      'python']
```

We can use the slicing operator[] to extract an item or range of items from a list. Index starts from 0 in Python.

Script.py

```
1. a=[5,10,15,20,25,30,35,40]  
2. #a[2] =15  
3. print("a[2] =",a[2])  
4. #a[0:3]=[5,10, 15]  
5. print("a[0:3]=",a[0:3])  
6. #a[5:]=[30,35, 40]  
7. print("a[5:]=",a[5:])
```

Lists are mutable, meaning; value of elements of a list can be altered.

```
>>> a =[1,2,3]  
>>>a[2]=4
```

Python Strings

String is sequence of Unicode characters. We can use single quotes or double quotes to represent strings. Multi-line strings can be denoted using triple quotes, ''' or ''''.

```
>>>s="This is a string"  
>>>s="amultiline"
```

Like list and tuple, slicing operator[] can be used with string. Strings are immutable.

Script.py

```
a={5,2,3,1,4}  
#printing set variable print("a = ",  
a)#data type of variable print(type(a))
```

We can perform set operations like union, intersection on two sets. Set have unique values. They eliminateduplicates. Since, setareunorderedcollection, indexinghasnomeaning. Hencetheslicing operator [] does not work. It is generally used when we have a huge amount of data. Dictionaries areoptimizedforretrievingdata. Wemustknowthekeytoretrievethethevalue. InPython, dictionaries are defined within braces {} with each item being a pair in the form key: value. Key and value can be of any type.

```
>>>d={'value','key':2}
```

```
>>>type(d)
```

```
<class'dict'>
```

We use key to retrieve the respective value. But not the other way around.

Script.py

```
d =  
{1:'value','key':2}print(type(d))print("d[1]  
=",d[1]);  
print("d['key']="  
",d['key']);#Generateserrorprint("d[2]=",d[2]);
```

Python if Statement Flowchart

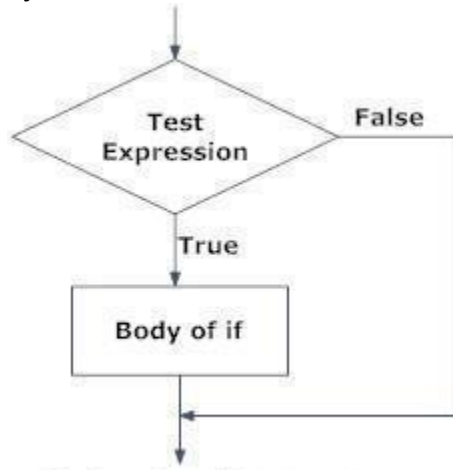


Fig: Operation of if statement.

Example: Python if Statement

#If the number is positive, we print an appropriate message num=3 if
num > 0:

```
print(num,"is a positive
```

```
number.")    print("This    is always printed.")
```

```
num = -1 if num > 0: print(num, "is a positive  
number.") print("This is also always printed.")
```

Python if..else Flow chart

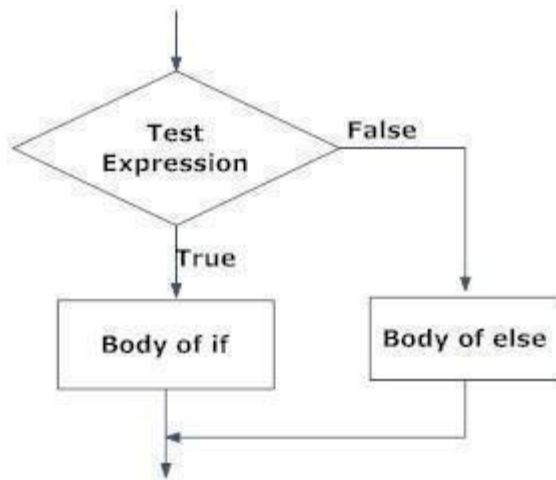


Fig: Operation of if...else statement

Example of if...else

#Program checks if the number is positive or negative#And displays an appropriate message

```
num = 3
```

```
#Trythesetwovariationsaswell.#num=-5 #
```

```
num = 0
```

```
ifnum>=0:print("PositiveorZero") else:
```

```
print("Negativenumber")
```

Intheaboveexample, when numis equalto3, the test expression is trueand body of if is executed and body of else is skipped.

Ifnumisequalto-5,the test expression is false and body of else is executed and body of if is skipped.

Ifnumisequalto0,thetest expressionistrueandbodyofif isexecutedandbodyof elseisskipped. Python

if...elif...else Statement Syntax if test expression:

Bodyofif

eliftest expression:

Python File Methods Files

File is a named location on disk to store related information. It is used to permanently store data in a non-volatile memory (e.g. hard disk). Since, random access memory (RAM) is volatile which loses its data when computer is turned off, we use files for future use of the data. When we want to read from or write to a file we need to open it first. When we are done, it needs to be closed, so that resources that are tied with the file are freed. Hence, in Python, a file operation takes place in the following order.

Open a file
Read or write (perform operation)
Close the file

How to open a file?

Python has a built-in function `open()` to open a file. This function returns a file object, also called a handle, as it is used to read or modify the file accordingly.

```
>>>f=open("test.txt")#open file in current directory
>>>f=open("C:/Python33/README.txt")#specifying full path
```

We can specify the mode while opening a file. In mode, we specify whether we want to read 'r', write 'w' or append 'a' to the file. We also specify if we want to open the file in text mode or binary mode. The default is reading in text mode. In this mode, we get strings when reading from the file. On the other hand, binary mode returns bytes and this is the mode to be used when dealing with non-text files like image or exe files.

Python File Modes

Mode	Description
'r'	Open a file for reading. (default)
'w'	Open a file for writing. Creates a new file if it does not exist or truncates the file if it exists.
'x'	Open a file for exclusive creation. If the file already exists, the operation fails.
'a'	Open for a pending at the end of the file without truncating it. Creates a new file if it does not exist.
't'	Open in text mode. (default)
'b'	Open in binary mode.
'+'	Open a file for updating (reading and writing)

```
f=open("test.txt")
#equivalent to 'r' or 'rt'
f=open("test.txt",'w')#write in text mode
f=open("img.bmp",'r+b')#read and write in binary mode
```

Unlike other languages, the character 'a' does not imply the number 97 until it is encoded using ASCII (or other equivalent encodings). Moreover, the default encoding is platform dependent. In windows, it is 'cp1252' but 'utf-8' in Linux. So, we must not also rely on the default encoding or else our code will behave differently in different platforms. Hence, when working with files in text mode, it is highly recommended to specify the encoding type.

```
f=open("test.txt",mode='r',encoding='utf-8')
```

Python Program with Raspberry PI with focus of interfacing external gadgets, controlling output, reading input from pins.

Light an LED through Python program.

Solution:

One of the biggest selling points of the Raspberry Pi is its GPIO, or General Purpose Input/Output ports. They are the little pins sticking out of the circuit board and allow you to plug various devices into your Raspberry Pi. With a little programming, you can then control them or detect what they are doing.

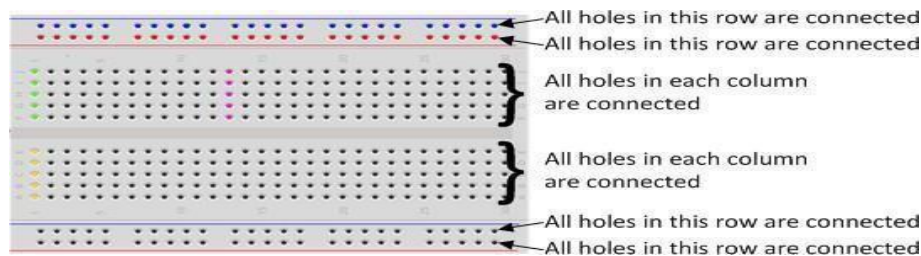
In this tutorial I am going to show you how to light an LED. In addition to your Raspberry Pi running Raspbian, what you will need is:

An LED

A 330ohm resistor

The Bread board:

The breadboard is a way of connecting electronic components to each other without having to solder them together. They are often used to test a circuit design before creating a Printed Circuit Board (PCB).



The LED:

When you pick up the LED, you will notice that one leg is longer than the other. The longer leg (known as the 'anode'), is always connected to the positive supply of the circuit. The shorter leg (known as the 'cathode') is connected to the negative side of the power supply, known as 'ground'.

LED stands for Light Emitting Diode, and glows when electricity is passed through it.

The Resistor:

You must ALWAYS use resistors to connect LEDs to the GPIO pins of the Raspberry Pi. The Raspberry Pi can only supply a small current (about 60mA). The LEDs will want to draw more, and if allowed to they will burn out the Raspberry Pi. Therefore putting the resistors in the circuit will ensure that only this small current will flow and the Raspberry Pi will not be damaged.

Jumper Wires:

Jumper wires are used on breadboards to 'jump' from one connection to another. The ones you will be using in this circuit have different connectors on each end. The end with the 'pin' will go into the Breadboard. The end with the piece of plastic with a hole in it will go onto the Raspberry Pi's GPIO pins.



The Raspberry Pi's GPIO Pins:

GPIO stands for **General Purpose Input Output**. It is how the Raspberry Pi can control and monitor the outside world by being connected to electronic circuits. The Raspberry Pi is able to control LEDs, turning them on or off, or motors, or many other things. It is also able to detect whether a switch has been pressed, or temperature, or light. In the CamJam EduKit you will learn to control LEDs and a buzzer, and detect when a button has been pressed. The diagram below left shows the pin layout for a Raspberry Pi Models A and B (Rev 2 - the original Rev 1 Pi is slightly different), looking at the Raspberry Pi with the pins in the top right corner. The new 40 pin Raspberry Pi's share exactly the same layout of pins for the top 13 rows of GPIO pins.

Building the Circuit:

The circuit consists of a power supply (the Raspberry Pi), an LED that lights when the power is applied, and

Models A & B

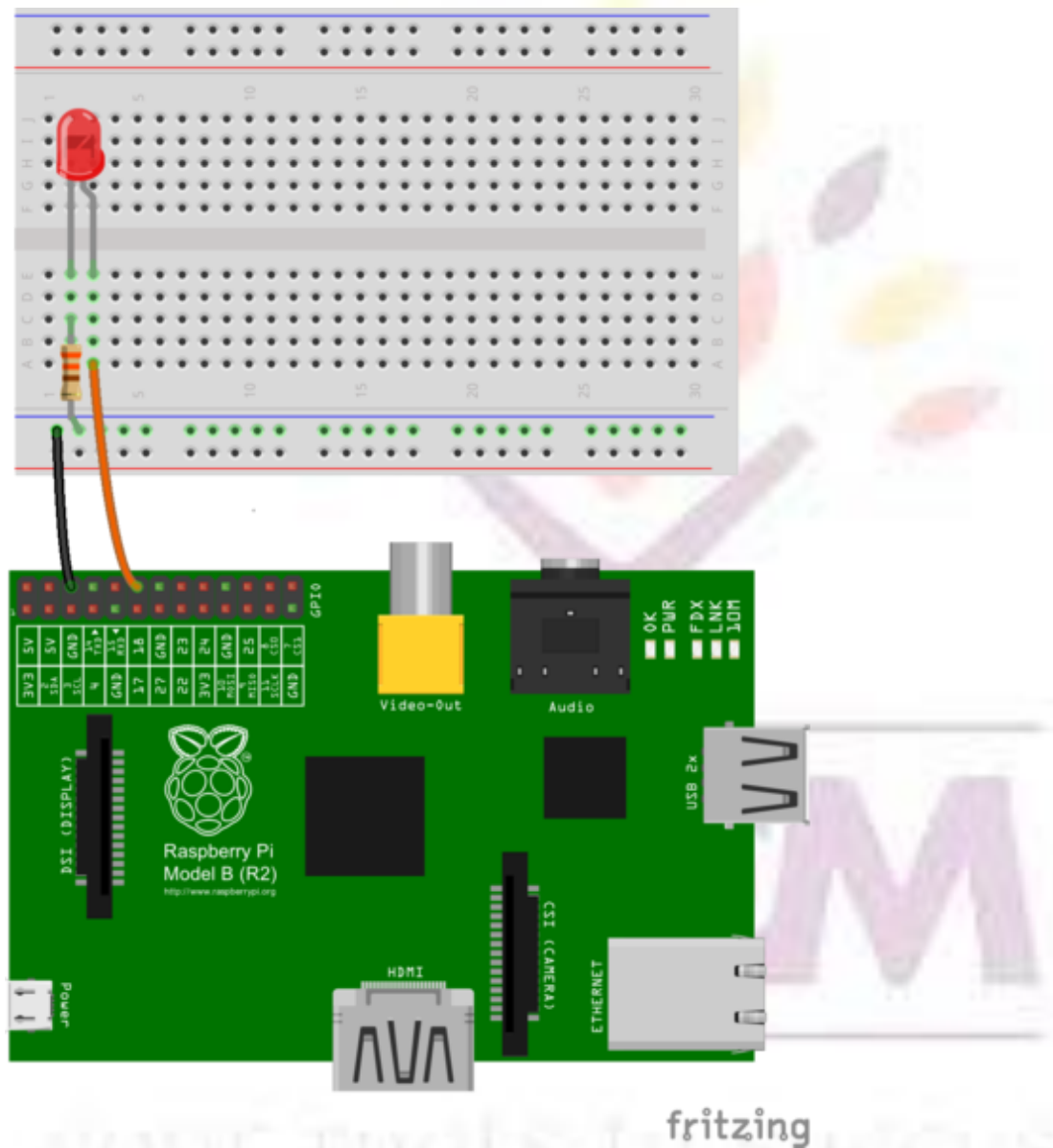
3V3	5V	
2	SDA	5V
3	SCL	GND
4	TXD	
GND	15	RXD
17	18	
27	GND	
22	23	
3V3	24	
10	MOSI	GND
9	MISO	25
11	SCLK	CS0
GND	CS1	

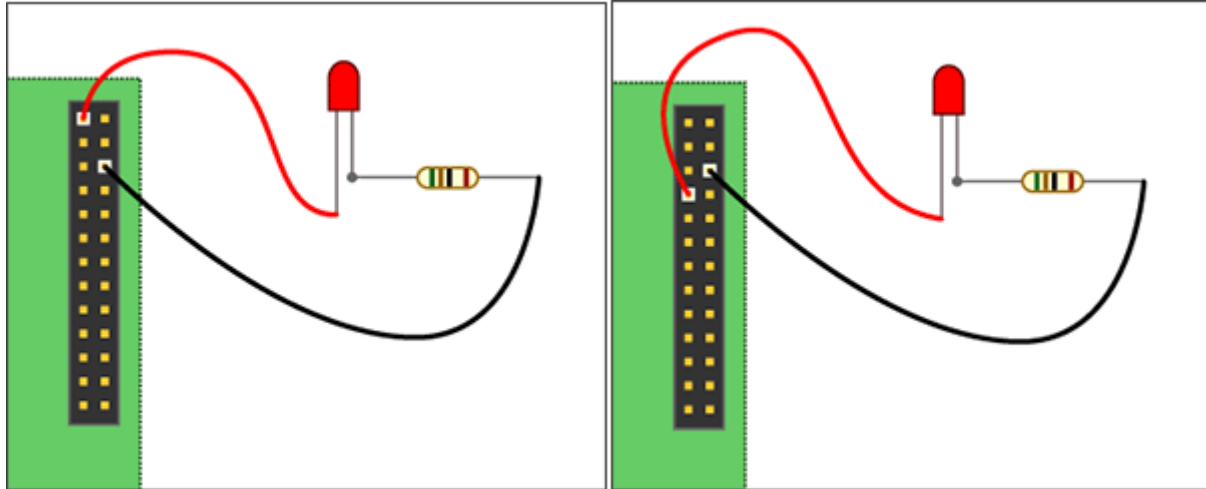
Models A+, B+ & Pi2

3V3	5V	
2	SDA	5V
3	SCL	GND
4	TXD	
GND	15	RXD
17	18	
27	GND	
22	23	
3V3	24	
10	MOSI	GND
9	MISO	25
11	SCLK	CS0
GND	CS1	
EPROM	EPROM	
5	GND	
6	12	
13	GND	
19	MISO	16
26	20	MOSI
GND	21	SCLK

are used to limit the current that can flow through the circuit.







```
print"LED on"GPIO.output(18,GPIO.HIGH)time.sleep(1)print "LED off"GPIO.output(18,GPIO.LOW)
```

Once you have typed all the code and checked it, save and exit the text editor with “Ctrl+x” then “y” then “enter”.

Running the Code:

To run this code type:

```
sudo python LED.py
```

You will see the LED turn on for a second and then turn off.

If your code does not run and an error is reported, edit the code again using `nano LED.py`.